

## CSE421: Digital Control

**Assignment 3****Discrete Block diagrams**

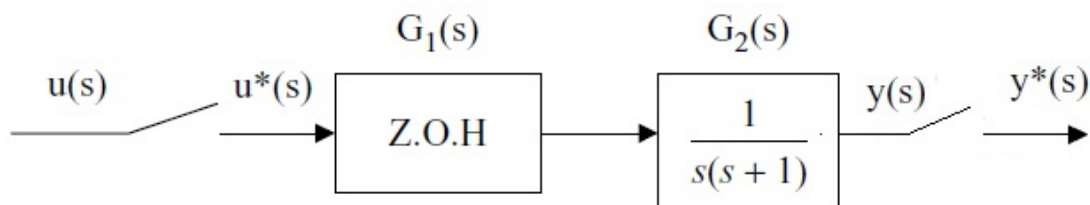
**Q1.** Assume that the following plant transfer functions are preceded by a zero-order hold. Compute the equivalent discrete transfer function  $G(z)$  using a sampling period  $T = 1$ . Check your answer with MATLAB.

$$(a) G(s) = \frac{1}{s^2}$$

$$(b) G(s) = \frac{1}{s(s+1)}$$

$$(c) G(s) = \frac{1}{s^2 - 1}$$

**Q2.** Calculate and plot the pulse response of the following system assuming that the sampling period  $T = 1$  sec.

**Solution:**

The transfer function of the ZOH is

$$G_1(s) = \frac{1 - e^{-Ts}}{s},$$

For this system, we can write

$$y(z) = G_1 G_2(z) u(z).$$

Now,  $T=1$  and

$$G_1G_2(s) = \frac{1 - e^{-Ts}}{s^2(s+1)},$$

Or by partial fractional expansion we can write

$$G_1G_2(s) = (1 - e^{-s}) \left( \frac{1}{s^2} - \frac{1}{s} + \frac{1}{s+1} \right).$$

From the z-transform tables

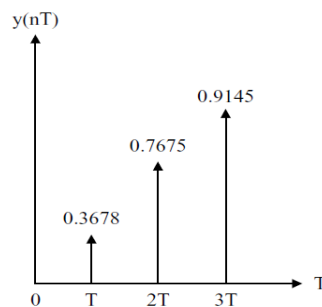
$$\begin{aligned} G_1G_2(z) &= (1 - z^{-1}) \left( \frac{z}{(z-1)^2} - \frac{z}{z-1} + \frac{z}{z-e^{-1}} \right) = \frac{ze^{-1} + 1 - 2e^{-1}}{(z-1)(z-e^{-1})} \\ &= \frac{0.3678z + 0.2644}{z^2 - 1.3678z + 0.3678}. \end{aligned}$$

For a pulse input,  $u(z) = 1$ . Therefore the pulse response will be given by

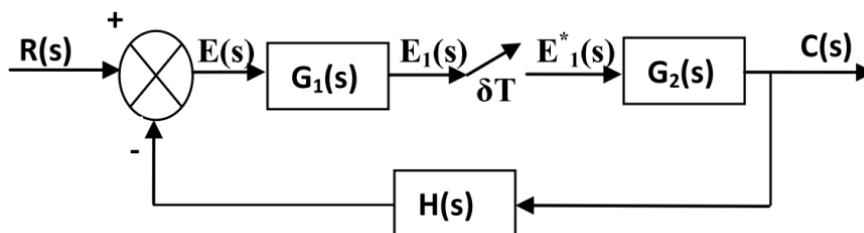
$$y(z) = G_1G_2(z)u(z) = G_1G_2(z) = \frac{0.3678z + 0.2644}{z^2 - 1.3678z + 0.3678}.$$

After long division, we obtain the time response

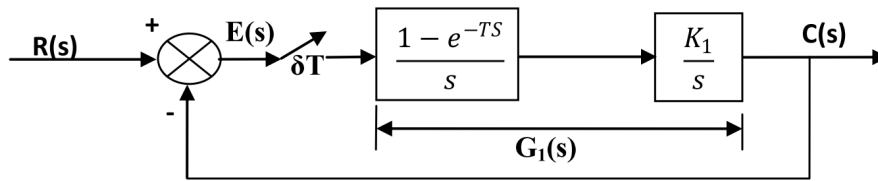
$$y(n) = 0.3678\delta(n-1) + 0.7675\delta(n-2) + 0.9145\delta(n-3) + \dots$$



**Q3.** Obtain the output  $C(z)$  for the discrete-time control system whose block diagram is shown below:



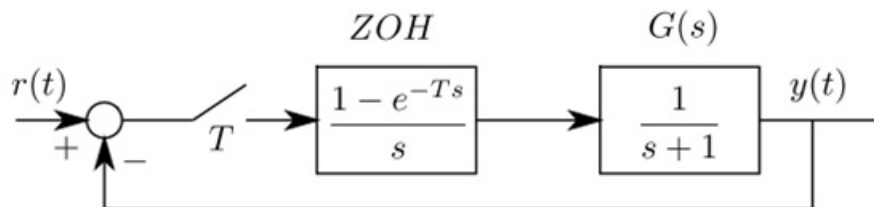
**Q4.** Obtain the output sequence  $c(kT)$  if the input  $r(t)$  is a unit step and  $T= 1$ sec for the discrete-time control system whose block diagram is shown below:



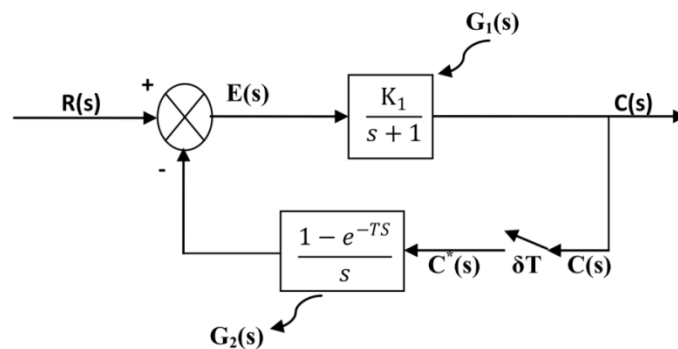
**Final answer:**

$$c(nT) = 1 - (1 - k_1)^n.$$

**Q5.** Sketch the step response  $y(t)$  of the system shown below for the three samples  $k = 0, 1, 2$ . Use sample period  $T = 1$ .



**Q6.** Obtain the output sequence  $c(kT)$  if the input  $r(t)$  is a unit step,  $T = 0.2$  sec and  $K_1 = 1$  for the discrete-time control system whose block diagram is shown below:



**Final answer:**

$$c(nT) = \frac{1}{2} [1 - (0.6374)^n] = \{0, 0.181, 0.297, 0.371, 0.418, \dots\}$$